RCC_AlCarController

Public Variables

// Car controller.
public RCC_CarControllerV3 CarController;

public RCC_AIWaypointsContainer waypointsContainer; // Waypoints Container. public int currentWaypointIndex = 0; // Current index in Waypoint Container. public string targetTag = "Player"; // Search and chase Gameobjects with tags. // AI Type public NavigationMode navigationMode; // Raycast distances and angles used for detecting obstacles at front of the AI vehicle. public float raycastLength = 3f; public float raycastAngle = 30f; public LayerMask obstacleLayers = -1; public GameObject obstacle; public bool useRaycasts = true; // Using forward and sideways raycasts to avoid obstacles. // Steer, Motor, And Brake inputs. Will feed RCC_CarController with these inputs. public float steerInput = Of; public float throttleInput = 0f; public float brakeInput = Of; public float handbrakeInput = Of; // Limit speed. public bool limitSpeed = false; public float maximumSpeed = 100f; // Smoothed steering. public bool smoothedSteer = true; // Counts laps and how many waypoints were passed. public int lap = 0; public int stopLap = 10; public bool stopAfterLap = false; public int totalWaypointPassed = 0; public int nextWaypointPassDistance = 20; public bool ignoreWaypointNow = false; // Detector radius. public int chaseDistance = 200; public int startFollowDistance = 300; public int stopFollowDistance = 30;

// Unity's Navigator.
public NavMeshAgent navigator;

// Detector with Sphere Collider. Used for finding target Gameobjects in chasing mode.
private SphereCollider detector;
public List<Transform> targetsInZone = new List<Transform>();
public List<RCC_AIBrakeZone> brakeZones = new List<RCC_AIBrakeZone>();

public Transform targetChase; // Target Gameobject for chasing. public RCC_AIBrakeZone targetBrake; // Target brakezone.

Events

// Firing an event when each RCC AI vehicle spawned / enabled.
public delegate void onRCCAISpawned(RCC_AICarController RCCAI);
public static event onRCCAISpawned OnRCCAISpawned;

// Firing an event when each RCC AI vehicle disabled / destroyed.
public delegate void onRCCAIDestroyed(RCC_AICarController RCCAI);
public static event onRCCAIDestroyed OnRCCAIDestroyed;